

Graph Algorithms with MapReduce S4230 Jay Urbain, Ph.D.

Credits:

•MapReduce: The Definitive Guide, Tom White

•Jeffery Dean and Sanjay Chemawat. *MapRecuce*

•Jimmy Lin and Chris Dyer. *Data Intensive Text Processing with MapReduce*

Today's Topics

- Introduction to graph algorithms and graph representations
- Single Source Shortest Path (SSSP) problem
 - Refresher: Dijkstra's algorithm
 - Breadth-First Search with MapReduce
- PageRank

What's a graph?

- G = (V,E), where
 - V represents the set of vertices (nodes)
 - E represents the set of edges (links)
 - Both vertices and edges may contain additional information
- Different types of graphs:
 - Directed vs. undirected edges
 - Presence or absence of cycles
- Graphs are everywhere:
 - Hyperlink structure of the Web
 - Physical structure of computers on the Internet
 - Interstate highway system
 - Social networks

Some Graph Problems

- Finding shortest paths
 - Routing Internet traffic and UPS trucks
- Finding minimum spanning trees
 - Telco laying down optical fiber
- Finding Max Flow
 - Airline scheduling
- Identify "special" nodes and communities
 - Breaking up terrorist cells, spread of avian flu
- Bipartite matching
 - Monster.com, Match.com
- PageRank, HITS, EdgeRank

Graphs and MapReduce

- Graph algorithms typically involve:
 - Performing computation at each node
 - Processing node-specific data, edge-specific data, and link structure
 - Traversing the graph in some manner
- Key questions:
 - How do you represent graph data in MapReduce?
 - How do you traverse a graph in MapReduce?

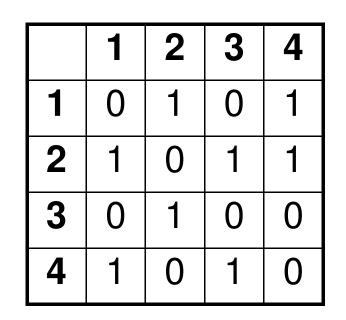
Representation Graphs

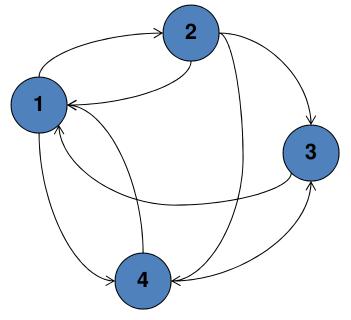
- G = (V, E)
 - A poor representation for computational purposes
- Two common representations
 - Adjacency matrix
 - Adjacency list

Adjacency Matrices

- Represent a graph as an *n* x *n* square matrix *M*
 - n = |V|

 $- M_{ij} = 1$ means a link from node *i* to *j*



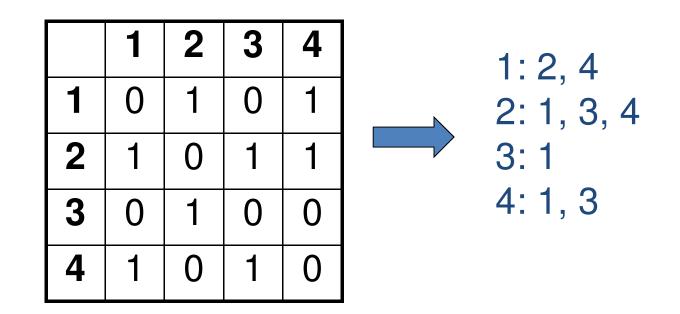


Adjacency Matrices: Critique

- Advantages:
 - Naturally encapsulates iteration over nodes
 - Rows and columns correspond to inlinks and outlinks
- Disadvantages:
 - Lots of zeros for sparse matrices
 - Lots of wasted space

Adjacency Lists

- Take adjacency matrices... and throw away all the zeros
- Represent only outlinks from a node

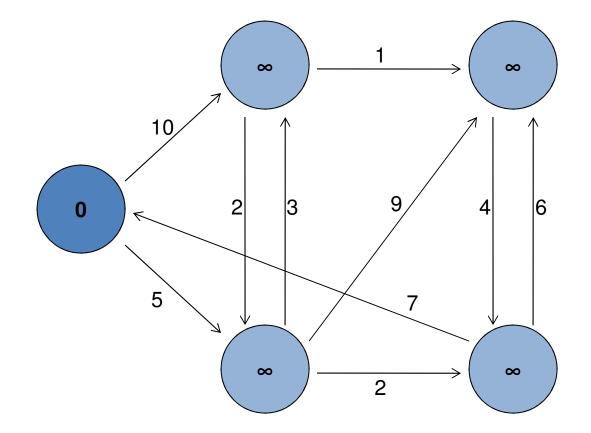


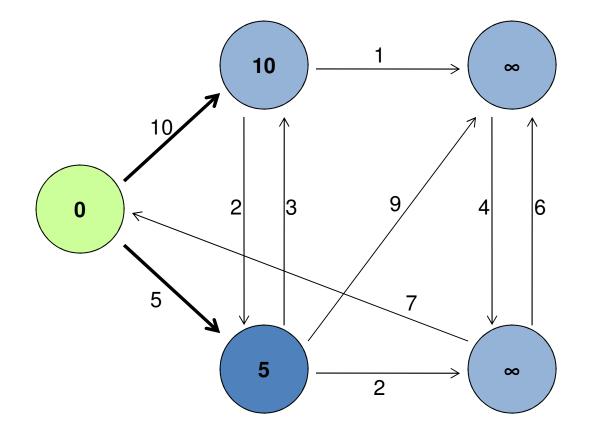
Adjacency Lists: Critique

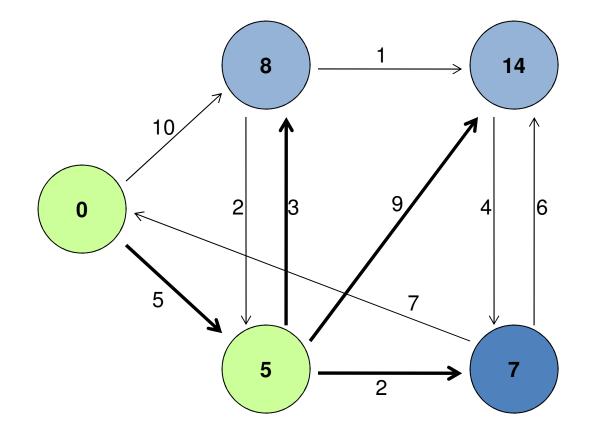
- Advantages:
 - Much more compact representation
 - Easy to compute over out-links
 - Graph structure can be broken up and distributed
- Disadvantages:
 - More difficult to compute over in-links

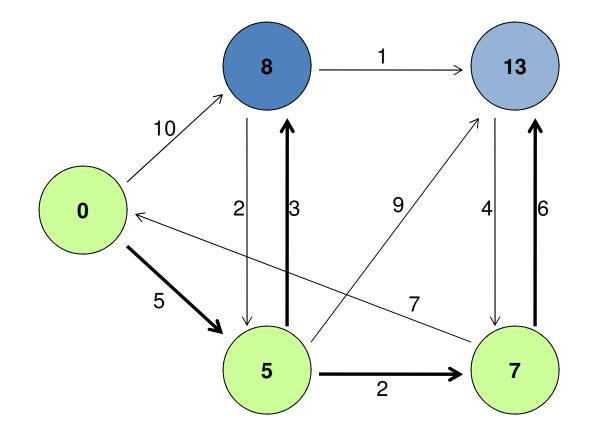
Single Source Shortest Path

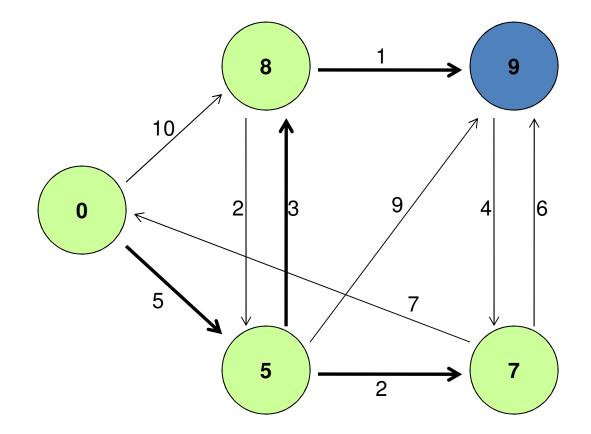
- **Problem:** find shortest path from a source node to one or more target nodes
- First, a refresher: Dijkstra's Algorithm

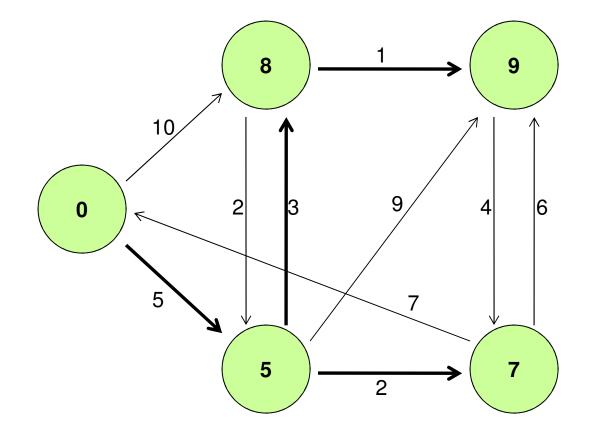












Single Source Shortest Path

- **Problem:** find shortest path from a source node to one or more target nodes
- Single processor machine: Dijkstra's Algorithm
- MapReduce: parallel Breadth-First Search (BFS)

Finding the Shortest Path

- First, consider equal edge weights
- Solution to the problem can be defined inductively
- Here's the intuition:
 - DistanceTo(startNode) = 0
 - For all nodes *n* directly reachable from startNode,
 DistanceTo(n) = 1
 - For all nodes n reachable from some other set of nodes S,
 DistanceTo(n) = 1 + min(DistanceTo(m), m ∈ S)

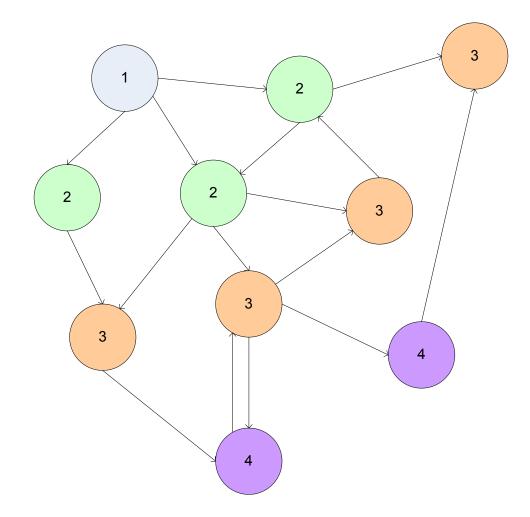
From Intuition to Algorithm

- A map task receives
 - Key: node *n*
 - Value: D (distance from start), points-to (list of nodes reachable from n)
- $\forall p \in \text{points-to: emit } (p, D+1)$
- The reduce task gathers possible distances to a given *p* and selects the minimum one

Multiple Iterations Needed

- This MapReduce task advances the "known frontier" by one hop
 - Subsequent iterations include more reachable nodes as frontier advances
 - Multiple iterations are needed to explore entire graph
 - Feed output back into the same MapReduce task
- Preserving graph structure:
 - Problem: Where did the points-to list go?
 - Solution: Mapper emits (*n*, points-to) as well

Visualizing Parallel BFS



Termination

- Does the algorithm ever terminate?
 - Eventually, all nodes will be discovered, all edges will be considered (in a connected graph)
- When do we stop?

Weighted Edges

- Now add positive weights to the edges
- Simple change: points-to list in map task includes a weight *w* for each pointed-to node
 - emit $(p, D+w_p)$ instead of (p, D+1) for each node p
- Does this ever terminate?
 - Yes! Eventually, no better distances will be found. When distance is the same, we stop
 - Mapper should emit (n, D) to ensure that "current distance" is carried into the reducer

Graph

- a: b, c
- b: c, d
- C:
- d:
- e:

Mapper (a, (0, (b,c))) Emit(b, (1, (c,d))) Emit(c, (1, ())) ... Reducer (b, (1, (c,d))) (b,1)<-min(b,1) output(b, (1, (c,d))) Reducer (c, (1, ()) (c,1)<-min(c,1)

output(c, (1, ()))

Mapper (b, (1, (c,d))) Emit(c, (2, ())) Emit(d, (2, ())) ... Reducer (c, (2, ())) (c,1)<- min(c,2) // no output Reducer (d, (2, ())) // no output (d,1)<- min(d,2) // no output

Comparison to Dijkstra

- Dijkstra's algorithm is more efficient
 - At any step it only pursues edges from the minimum-cost path inside the frontier
- MapReduce explores all paths in parallel
 - Divide and conquer
 - Throw more hardware at the problem!

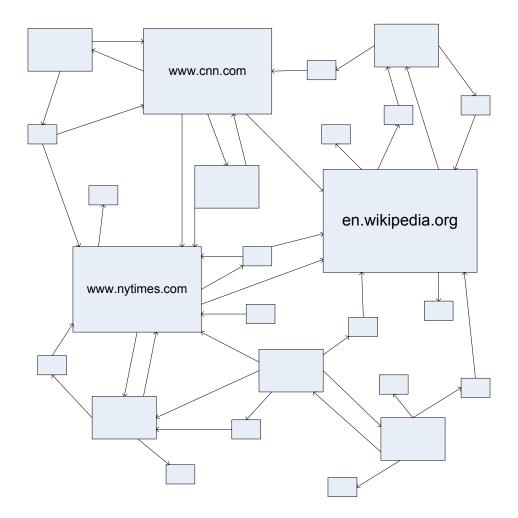
General Approach

- MapReduce is adept at manipulating graphs
 - Store graphs as adjacency lists
- Graph algorithms with MapReduce:
 - Each map task receives a node and its outlinks
 - Map task compute some function of the link structure, emits value with target as the key
 - Reduce task collects keys (target nodes) and aggregates
- Iterate multiple MapReduce cycles until some termination condition:
 - Remember to "pass" graph structure from one iteration to next

Random Walks Over the Web

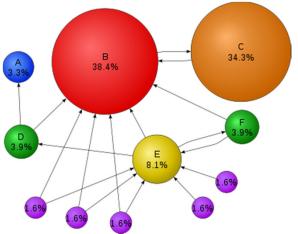
- Model:
 - User starts at a random Web page
 - User randomly clicks on links, surfing from page to page
- What's the amount of time that will be spent on any given page?
- This is PageRank

PageRank: Visually



PageRank

- Initially developed at Stanford University by Google founders, Larry Page and Sergey Brin, in 1995.
- Program implemented by Google to rank any type of recursive "documents" using MapReduce.
- Led to a functional prototype named Google in 1998.
- Still provides an important function for Google's web search tools.



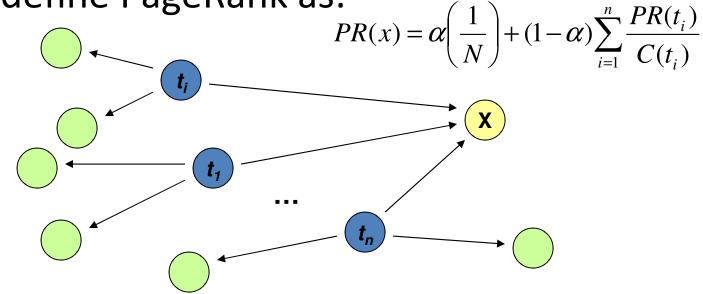
PageRank

- Assume a small universe of four web pages: A, B, C and D. The initial approximation of PageRank would be evenly divided between these four documents.
- Each document would begin with an estimated PageRank of 0.25.
- If the only links in the system were from pages B, C, and D to A, each link would transfer 0.25 PageRank to A upon the next iteration, for a total of 0.75.

PR(A) = PR(B) + PR(C) + PR(D).

PageRank: Defined

- Given page x with in-bound links $t_1...t_n$, where
 - -C(t) is the out-degree of t
 - α is probability of random jump
 - N is the total number of nodes in the graph
- We can define PageRank as:



PageRank

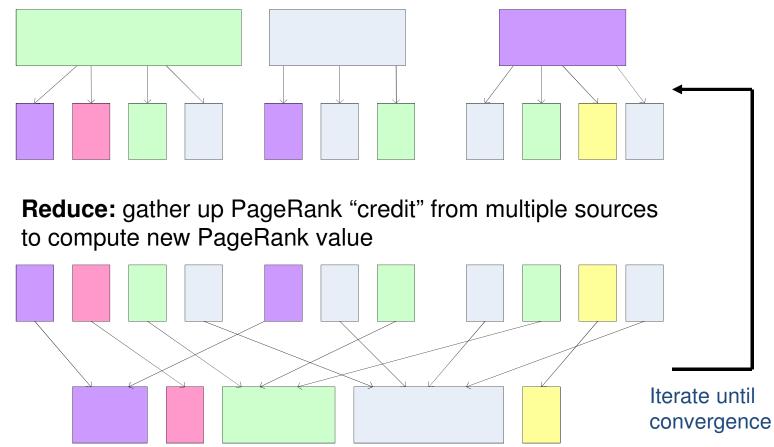
- Simulates a "random-surfer"
- Begins with pair (URL, list-of-URLs)
- Maps to (URL, (PR, list-of-URLs))
- Maps again taking above data, and for each *u* in list-of-URLs returns (*u*, PR/|list-of-URLs|), as well as (*u*, new-list-of-URLs)
- Reduce receives (URL, list-of-URLs), and many (URL, value) pairs and calculates (URL, (new-PR, list-of-URLs))

Computing PageRank

- Properties of PageRank
 - Can be computed iteratively
 - Effects at each iteration is local
- Sketch of algorithm:
 - Start with seed *PR*_i values
 - Each page distributes PR_i "credit" to all pages it links to
 - Each target page adds up "credit" from multiple in-bound links to compute PR_{i+1}
 - Iterate until values converge

PageRank in MapReduce

Map: distribute PageRank "credit" to link targets



...

PageRank: Issues

- Is PageRank guaranteed to converge? How quickly?
- What is the "correct" value of α , and how sensitive is the algorithm to it?
- What about dangling links?
- How do you know when to stop?